

Jan 25, 2019

Velocity and acceleration

Review:

$$x = A \cos(\omega t + \phi)$$

$$v = \frac{dx}{dt} = -\omega A \sin(\omega t + \phi)$$

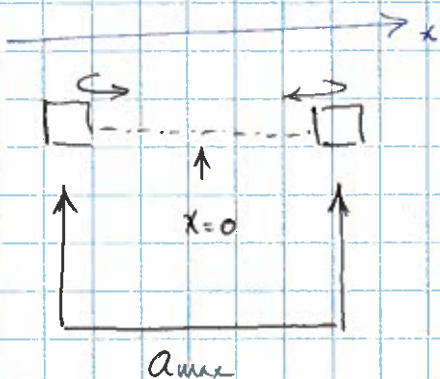
$$a = \frac{d^2x}{dt^2} = -\omega^2 A \cos(\omega t + \phi) = -\omega^2 x$$

$$\frac{d^2x}{dt^2} = -\omega^2 x, \quad \omega = \sqrt{\frac{k}{m}}$$

all cyclic

→ $v_{max} = \omega A$, where? at $x=0$

and $a_{max} = \omega^2 A$, at $x = \pm A$



Note that $v=0$ at the endpoints (for a moment)

example:

~~14-1A~~ 18

(to get a feel for size of SHM acceleration)

(demo)

tuning fork:

441 cycles/second

264 Hz (vibrating)

$A = 1.5 \text{ mm}$ (at the tip)

max acceleration of the tip?

$$a_{max} = \omega^2 A$$

$$\omega = 2\pi f = \frac{2\pi}{T} = 2\pi F = 1659 \text{ s}^{-1}$$

$$a_{max} = \omega^2 A = (1659)^2 (1.5 \times 10^{-3} \text{ m})$$

$$= 4127 \text{ m/s}^2$$

$$\sim \frac{1200}{480} \text{ g's (1)}$$

f [cycles/sec]
 T [sec/cycle]

$$f = \frac{1}{T}$$

Energy of SHM (Use spring as example, but results can be generalized)

SPRING: $K = \frac{1}{2}mv^2$ and $U = \frac{1}{2}kx^2$

total energy $E = K + U$, let $\phi = 0$ for convenience

$$= \frac{1}{2}mv^2 + \frac{1}{2}kx^2$$

$$= \frac{1}{2}m(\omega^2 A^2 \sin^2 \omega t) + \frac{1}{2}k(A^2 \cos^2 \omega t)$$

$$= \frac{1}{2}m\omega^2 A^2 \sin^2 \omega t + \frac{1}{2}k A^2 \cos^2 \omega t$$

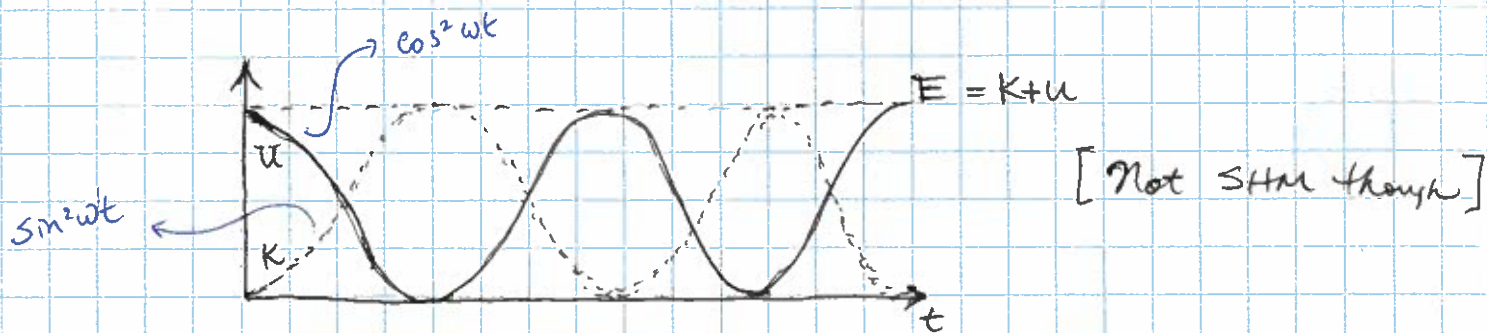
$$= \frac{1}{2} \cancel{m} \frac{k}{m} A^2 \sin^2 \omega t + \frac{1}{2}k A^2 \cos^2 \omega t$$

$$= \frac{1}{2}k A^2 (\sin^2 \omega t + \cos^2 \omega t)$$

$$= \frac{1}{2}k A^2$$

① Constant total $E \propto$ ② square of the amplitude.

K and U oscillate out of phase relative to each other:



Where is $K = U$? $\frac{1}{2}mv^2 = \frac{1}{2}kx^2 \Rightarrow x = \pm \sqrt{\frac{m}{k}} v$

WHEN?

$$\Rightarrow \rightarrow A \cos \omega t = \pm \sqrt{\frac{m}{k}} A \omega \sin \omega t$$

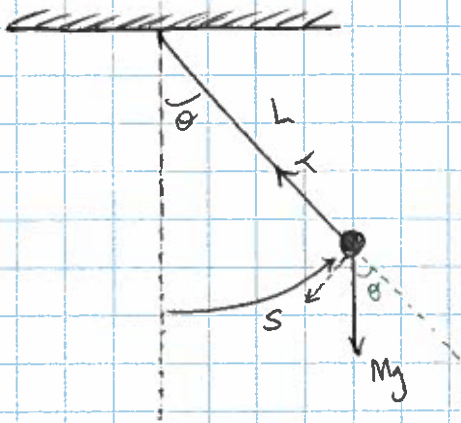
$$\cos \omega t = \pm \sqrt{\frac{m}{k}} \omega \sin \omega t \Rightarrow \tan \omega t = \pm 1$$

$$\therefore \omega t = \frac{\pi}{4}, \frac{3\pi}{4}, \frac{5\pi}{4}, \dots \Rightarrow t = \frac{\pi}{4\omega}, \frac{3\pi}{4\omega}, \frac{5\pi}{4\omega}, \dots$$

Another example of a system that has SHM:

The Pendulum

(3)



$s = L \cdot \theta$ displacement

restoring force $F = -mgs \sin \theta$ (like $-kx$)

equation of motion

Newton's 2nd law

$\therefore ma = m \frac{d^2 s}{dt^2} = -mgs \sin \theta$

$L \frac{d^2 \theta}{dt^2} = -g s \sin \theta$

$\frac{d^2 \theta}{dt^2} = -\frac{g}{L} s \sin \theta$

Recall

(SHM: $\frac{d^2 x}{dt^2} = (-\omega^2) x = -\frac{k}{m} x$)

approximation: $\sin \theta \approx \theta$ (radians) for small θ
 $-\frac{\theta^3}{3!} + \dots$

So $\frac{d^2 \theta}{dt^2} \approx -\frac{g}{L} \theta$

\Rightarrow solution $\theta = \theta_0 \cos(\omega t + \phi)$ with $\omega = \sqrt{\frac{g}{L}}$

period of oscillation $T = \frac{2\pi}{\omega} = 2\pi \sqrt{\frac{L}{g}}$

• mid. of mass, mid. of $A \theta_0$

\rightarrow Galileo, Huygens

applications

- \rightarrow pendulum clock (accurate) (grandfather clock)
 - \hookrightarrow until ~ 1927 \rightarrow quartz clock
- \rightarrow Use pendulum for accurate measurement of g . (at different locations)