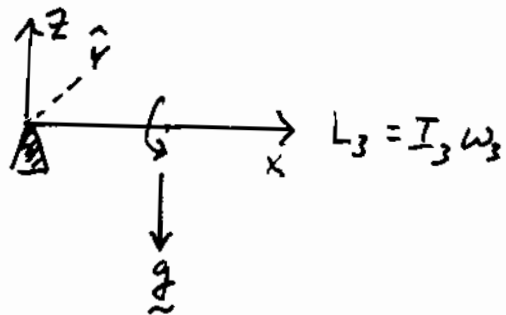


Horizontal Precession of Gyroscope:

Elementary view



$$\underline{r} = (l, 0, 0)$$

$$\underline{F} = (0, 0, -mg)$$

$$\underline{\tau} = \underline{r} \times \underline{F} = mgl (\hat{O}\hat{Y}) = mgl \hat{\phi} = \frac{mgl}{I_3} (\hat{O}\hat{Z} \times \underline{L}) = \frac{d\underline{L}}{dt}$$

$\dot{\alpha} = mgl/I_3$ precesses around OZ .

More detailed study: $\dot{\alpha}_0 = \frac{P_x - P_y \cos \beta_0}{I_1 \sin^2 \beta_0} \rightarrow \frac{P_x}{I_1}$ if $\beta_0 = \pi/2$

But $P_y \cos \beta \approx P_x$ near β_0 so must be careful.

β_0 determined by $\left(\frac{\partial V}{\partial \beta}\right)_{\beta_0} = 0$

$$\cos^2 \beta_0: P_x^2 - 2P_x P_y \cos \beta_0 + P_y^2 - P_x P_y \frac{\sin^2 \beta_0}{\cos \beta_0} + I_1 mgl \frac{\sin^4 \beta_0}{\cos \beta_0} = 0$$

$$\begin{aligned} (P_y \cos \beta_0)^2 - (P_y \cos \beta_0) P_x \left(\frac{2 \cos^2 \beta_0 + \sin^2 \beta_0}{1 + \cos^2 \beta_0} \right) + P_x^2 \cos^2 \beta_0 & \text{small} \\ + I_1 mgl \frac{\sin^4 \beta_0 \cos \beta_0}{\approx 1 - 2 \cos^2 \beta_0} & = 0 \end{aligned}$$

Rule: keep $(P_y \cos \beta_0)$ or P_x

but drop relative order $\cos^2 \beta_0$ terms.

$$(P_y \cos \beta_0)^2 - P_x (P_y \cos \beta_0) + I_1 mgl \cos \beta_0 \approx 0 \quad (\text{order of } \cos^2 \beta_0)$$

$$\cos \beta_0 \{ P_y^2 \cos \beta_0 - P_x P_y + I_1 mgl \} = 0$$

$$\cos \beta_0 \approx \frac{P_x}{P_y} - \frac{I_1 mgl}{P_y^2} \quad \text{is solution for minimum of } V_{\text{eff}}(\beta)$$

Hence, if we look for solutions with $\beta_0 \approx \pi/2$

we have (1) $\cos \beta_0 \approx \frac{P_x}{P_y} - \frac{I_1 mgl}{P_y^2}$ $\beta_0 \approx \pi/2 - \frac{P_x}{P_y} + \dots$

(2) $P_y = \underline{L} \cdot \hat{e}_y = \underline{L} \cdot \hat{e}_z \Rightarrow |L| = P_y$ lies close to the symmetry axis

(3) $\dot{\gamma}_0 = P_y \left(\frac{1}{I_3} + \frac{\cot^2 \beta}{I_1} \right) - \frac{P_x \cos \beta}{I_1 \sin^2 \beta} \approx \frac{P_y}{I_3} = \frac{|L|}{I_3}$

is the mean rate of spin around symmetry axis

(4) precession rate $\dot{\alpha}_0 = \frac{P_x - P_y \cos \beta}{I_1 \sin^2 \beta} \approx \frac{mgl}{P_y} = \frac{mgl}{|L|}$

varies inversely with $|L|$.

(5) $\Omega^2 = \frac{P_x P_y - I_1 mgl}{I_1^2 \cos \beta_0} \approx \frac{P_x P_y}{I_1^2 \cos \beta_0} \approx \frac{P_y^2}{I_1^2}$

nutaton rate $\Omega \approx \frac{P_y}{I_1} = \frac{|L|}{I_1}$ varies linearly with L .

The combination of rapid nutation with slow precession is called pseudo-regular precession.

(The nutation is hardly visible.)