

Charged particle in an EM field

Lorentz force $\vec{F} = q (\vec{E} + \vec{v} \times \vec{B})$

where $\vec{E} = -\vec{\nabla}\phi - \frac{\partial \vec{A}}{\partial t}$ $\vec{B} = \vec{\nabla} \wedge \vec{A}$

$\phi(\vec{r}, t)$ = scalar potential

$\vec{A}(\vec{r}, t)$ = vector potential

What Lagrangian gives the Lorentz force?

$$L = \frac{1}{2} m \dot{\vec{r}}^2 + q \dot{\vec{r}} \cdot \vec{A}(\vec{r}, t) - q \phi(\vec{r}, t)$$

check $\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}_\alpha} \right) = \frac{\partial L}{\partial q_\alpha}$

check the x-component: $\frac{\partial L}{\partial \dot{x}} = m \dot{x} + q A_{0x} = P_{0x}$

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{x}} \right) = m \ddot{x} + q \left(\frac{\partial A_{0x}}{\partial t} + \underbrace{\vec{\nabla} A_{0x} \cdot \dot{\vec{r}}}_{\frac{\partial_x A_{0x}}{\partial x} \dot{x} + \frac{\partial_y A_{0x}}{\partial y} \dot{y} + \frac{\partial_z A_{0x}}{\partial z} \dot{z}} \right)$$

A_{0x} varies in time both because of its explicit time-dependence and because of its dependence on particle position $\vec{r}(t)$

RHS: $\frac{\partial L}{\partial x} = q \dot{\vec{r}} \cdot \frac{\partial \vec{A}}{\partial x} - q \frac{\partial \phi}{\partial x}$
i.e. $q \left(\dot{x} \frac{\partial A_x}{\partial x} + \dot{y} \frac{\partial A_y}{\partial x} + \dot{z} \frac{\partial A_z}{\partial x} \right)$

Combine: terms in \dot{x} cancel

(2)

$$m\ddot{x} + q\left(\frac{\partial A_x}{\partial t} + \dot{y} \partial_y A_x + \dot{z} \partial_z A_x\right) = q\left(\dot{y} \frac{\partial}{\partial x} A_y + \dot{z} \frac{\partial}{\partial x} A_z\right) - q \frac{\partial \phi}{\partial x}$$

$$m\ddot{x} = \cancel{q\dot{x}} q\left(\underbrace{-\frac{\partial \phi}{\partial x} - \frac{\partial A_x}{\partial t}}_{E_x} + \dot{y} \partial_x A_y + \dot{z} \partial_x A_z - \dot{y} \partial_y A_x - \dot{z} \partial_z A_x\right)$$

$$(\vec{v} \cdot \vec{B})_{xc} = \left[\vec{v} \wedge (\vec{v} \wedge \vec{A})\right]_{xc}$$

$$[\vec{v} \wedge (\vec{v} \wedge \vec{A})]_i = \cancel{v_j v_k A_l} \cancel{v_l A_m}$$

$$= \epsilon_{ijk} v_j (\vec{v} \wedge \vec{A})_k = \epsilon_{ijk} v_j \epsilon_{klm} v_l A_m = \epsilon_{ijk} \epsilon_{klm} v_j v_l A_m$$

but $\epsilon_{ijk} \epsilon_{klm} = \epsilon_{kij} \epsilon_{klm} = \delta_{il} \delta_{jm} - \delta_{im} \delta_{jl}$

so $[\vec{v} \wedge (\vec{v} \wedge \vec{A})]_i = (\delta_{il} \delta_{jm} - \delta_{im} \delta_{jl}) v_j v_l A_m$

put $i=x$ $\Rightarrow l=x$ $\Rightarrow m=x$

$$= v_j \partial_x A_j - v_j \partial_j A_x$$

$$= v_{xc} \partial_x A_x + v_y \partial_x A_y + v_z \partial_x A_z$$

$$- v_{xc} \partial_x A_x - v_y \partial_y A_x - v_z \partial_z A_x \quad \checkmark$$

Same as

Note ① L contains $\dot{\vec{r}}$ i.e. linear in time derivative. ③
 L cannot be separated into two parts, $T' - V'$,
 one quadratic in $\dot{\vec{r}}$ and one independent of it.

② $\vec{p} = m \dot{\vec{r}} + q \vec{A}$ canonical momentum

③ Hamiltonian

$$H = \vec{p} \cdot \dot{\vec{r}} - L = m \dot{\vec{r}}^2 + q \dot{\vec{r}} \cdot \vec{A} - \frac{1}{2} m \dot{\vec{r}}^2 - q \dot{\vec{r}} \cdot \vec{A} + q \phi$$

$$= \frac{1}{2} m \dot{\vec{r}}^2 + q \phi$$

but $\dot{\vec{r}} = \frac{\vec{p} - q \vec{A}}{m}$

$$H = \frac{(\vec{p} - q \vec{A})^2}{2m} + q \phi$$

If \vec{E} and \vec{B} are time independent, can choose ϕ and \vec{A} to also be time independent

$$\Rightarrow H = E = \text{const}$$

(4)

Phase space

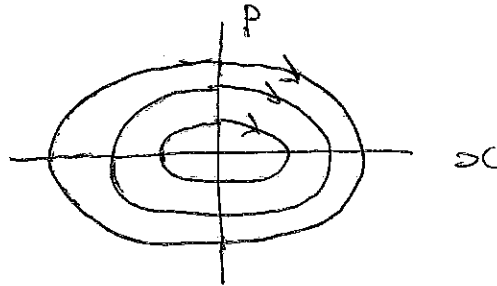
Hamilton's approach to classical mechanics lives in a $2n$ dimensional space called phase space: (x, p)

Example simple harmonic oscillator

$$H = \frac{p^2}{2m} + \frac{1}{2}kx^2 = \frac{p^2}{2m} + \frac{1}{2}m\omega^2 x^2$$

$$\text{where } \omega = \sqrt{\frac{k}{m}}$$

Contours of constant energy $H = E$ are ellipses



Phase space

Hamilton's eqns: $\dot{x} = \frac{\partial H}{\partial p} = \frac{p}{m}$

$$\dot{p} = -\frac{\partial H}{\partial x} = -m\omega^2 x$$

Liouville's theorem

General motion in phase space might be complicated, but according to Hamilton's equations it is divergenceless, i.e. they generate "incompressible flow".

Divergence : $\nabla \cdot V = \partial_x V_x + \partial_y V_y$ (in 2D)

(5)

In phase space : $\sum_{i=1}^n \left(\frac{\partial \dot{q}_i}{\partial q_i} + \frac{\partial \dot{p}_i}{\partial p_i} \right)$

$$= \sum_{i=1}^n \left(\frac{\partial^2 H}{\partial q_i \partial p_i} - \frac{\partial^2 H}{\partial p_i \partial q_i} \right) = 0$$

A blob of phase space "fluid" has zero divergence.

A volume element in phase space is preserved under Hamiltonian fluid.

Lagrangian ~~mechanics~~ dynamics do not conserve volume in (x, \dot{x}) "space".

In Hamiltonian dynamics we consider p and q on equal footing as a single set of $2n$ coords Z .

$$\vec{Z} = (q_1, q_2, \dots, q_n; p_1, p_2, \dots, p_n)$$

then Hamilton's equations: $\dot{\vec{Z}} = J \cdot \nabla H(Z)$

$$\nabla = (\partial_{z_1}, \partial_{z_2}, \dots, \partial_{z_n})$$

$$J = \begin{pmatrix} 0 & \mathbb{1} \\ -\mathbb{1} & 0 \end{pmatrix}$$

$2n \times 2n$ matrix

"The symplectic matrix"

$\mathbb{1} = n \times n$ unit matrix

Poisson brackets

6

Time-dependence of dynamical quantities can be formulated elegantly in the Hamiltonian picture

consider $f = f(p, q, t)$ (some function)

$$\frac{df}{dt} = \sum_{i=1}^n \left(\frac{\partial f}{\partial q_i} \frac{dq_i}{dt} + \frac{\partial f}{\partial p_i} \frac{dp_i}{dt} \right) + \frac{\partial f}{\partial t}$$

$$= \sum_{i=1}^n \left(\frac{\partial f}{\partial q_i} \frac{\partial H}{\partial p_i} - \frac{\partial f}{\partial p_i} \frac{\partial H}{\partial q_i} \right) + \frac{\partial f}{\partial t}$$

$$= [f, H]_{q,p} + \frac{\partial f}{\partial t}$$

N.B. writing it as $[H, f]$ is a convention
could equally write $[f, H]$

$[f, H]$ = the Poisson bracket of f with H .

There is a close analogy to ~~Q.M.~~ commutators in Q.M.

Can write the Poisson bracket for any pair of dynamical quantities

$$[f, g]_{q,p} = \sum_{i=1}^n \left(\frac{\partial f}{\partial q_i} \frac{\partial g}{\partial p_i} - \frac{\partial f}{\partial p_i} \frac{\partial g}{\partial q_i} \right)$$

If a quantity is explicitly time independent ($f = f(p, q)$) and its Poisson bracket with H vanishes, then f is a constant of the motion.

Poisson bracket of H with itself is zero. So energy of a time-independent system ($H = E$) is a constant of the motion

(7)

Compare with the Heisenberg equations of motion:
 $i\hbar \dot{A} = [A, \hat{H}]$ (actually first written down by Dirac)

$i\hbar \dot{A} = [A, \hat{H}]$ ← commutator

Note that for three functions f, g, h

$$[f, g] = -[g, f]$$

$$[f+g, h] = [f, h] + [g, h]$$

$$[fg, h] = f[g, h] + g[f, h]$$

$$[f, [g, h]] + [g, [h, f]] + [h, [f, g]] = 0 \quad (\text{Jacobi's identity})$$

These properties show that Poisson brackets satisfy a Lie Algebra.
These same identities are satisfied by Poisson brackets and commutators.

If we choose f, g, h to be canonical variables

$$[q_a, q_b] = \sum_{i=1}^n \left(\frac{\partial q_a}{\partial q_i} \frac{\partial q_b}{\partial p_i} - \frac{\partial q_a}{\partial p_i} \frac{\partial q_b}{\partial q_i} \right) = 0$$

- always zero - always zero

$$[p_a, p_b] = 0$$

$$[q_a, p_b] = \sum_{i=1}^n \left(\frac{\partial q_a}{\partial q_i} \frac{\partial p_b}{\partial p_i} - \frac{\partial q_a}{\partial p_i} \frac{\partial p_b}{\partial q_i} \right) = \delta_{ab}$$

$\underbrace{\quad}_{=0} \quad \quad \quad \underbrace{\quad}_{=0}$

cf QM $[q_a, p_b] = i\hbar \delta_{ab}$

Dirac's rule for quantization $[,]_{\text{classical}} \rightarrow \frac{[,]_{\text{quantum}}}{i\hbar}$

There are cases where the derivatives appear in q.m. version, e.g. the very useful velocities.

(8)

$$[\hat{x}_i, F(\vec{p})] = i\hbar \frac{\partial F}{\partial p_i}$$

$$[\hat{p}_i, G(x)] = -i\hbar \frac{\partial G}{\partial x_i}$$

Can be proved using
 $[A, BC] = [A, B]C + B[A, C]$
 repeatedly

Classical proof

Take first one : $[x, F(p)] = \frac{\partial x}{\partial x} \frac{\partial F}{\partial p} - \frac{\partial x}{\partial p} \frac{\partial F}{\partial x}$

$\underbrace{\hspace{4em}}_{=0} \quad \underbrace{\hspace{4em}}_{=0}$

Now apply $[,]_{\text{classical}} \rightarrow \frac{[,]_{\text{quantum}}}{i\hbar}$

$$[x, F(p)] \rightarrow \frac{[\hat{x}_i, F(\vec{p})]}{i\hbar} \stackrel{=}{=} \frac{\partial F}{\partial p}$$

as req'd.

Note: Quantum commutators also work for cases when there is no classical analogue, e.g. spin