

# Analytical Mechanics

Lecture 1

①

## Review of angular momentum

Chpt. 3 in Kibble & Berkshire

$$\vec{J} \equiv \vec{r} \times \vec{p} = m \vec{r} \times \dot{\vec{r}}$$

Ang. mom. about the origin  
of a particle at position  $\vec{r}$ ,  
and moving with momentum  $\vec{p}$ .  
 $\vec{J}$  depends on ~~axis~~ <sup>point</sup> about which  
we evaluate it

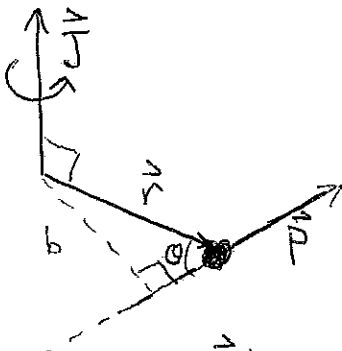
Rate of change of  $\vec{J}$

$$\dot{\vec{J}} = m \frac{d}{dt} (\vec{r} \times \dot{\vec{r}}) = m \left( \underbrace{\dot{\vec{r}} \times \dot{\vec{r}}}_{=0} + \underbrace{\vec{r} \times \ddot{\vec{r}}}_{\vec{r} \times \vec{a}}$$

$$= \vec{r} \times \vec{F} \equiv \vec{Q} \quad \text{the torque} \\ \text{(or "moment of } \vec{F} \text{" )}$$

i.e.  $\boxed{\dot{\vec{J}} = \vec{Q}}$

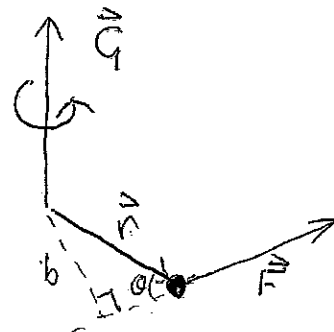
Ang. Mom.



$b =$  perp dist.  
to origin  
of  $\vec{p}$

$$|\vec{J}| = r p \sin \theta$$

Torque



$$|\vec{Q}| = r F \sin \theta$$

## Central forces : conservation of Ang. Mom.

②

An external force is CENTRAL if it is always directed towards or away from a fixed point.

If we choose this point to be the origin then  $\vec{F}$  is  $\parallel$  to  $\vec{r}$ . Then

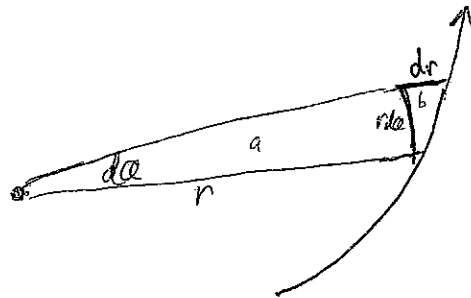
$$\vec{\tau} = \vec{r} \times \vec{F} = 0$$

$$\Rightarrow \vec{J} = \text{const.} \quad \text{conservation of A.M.}$$

Because  $\vec{J}$  is a vector :

1). Direction of  $\vec{J}$  is constant.  $\vec{J}$  is  $\perp$  to plane of  $\vec{r}$  and  $\vec{v}$   
 $\Rightarrow$  if  $\vec{J}$  is fixed then  $\vec{r}$  and  $\vec{v}$  always lie in fixed plane  
 i.e. motion is confined to initial plane.

2) Magnitude of  $\vec{J}$  is constant. In a short time interval, the change in the polar coords  $(r, \theta)$  are  $dr$  and  $d\theta$ .  
 Distance travelled in radial direction :  $dr$   
 " " " transverse " :  $r d\theta$



$$\begin{aligned} \text{Area of triangle a} &= \frac{1}{2} r^2 d\theta \\ &= \frac{1}{2} r^2 d\theta \end{aligned}$$

$$v_r = \dot{r} \quad v_\theta = r \dot{\theta}$$

$$\begin{aligned} \text{Area of triangle b} &\approx r d\theta dr \approx 0 \\ &(\text{? small quantities}) \end{aligned}$$

$$\Rightarrow |\vec{J}| = m r v_\theta = m r^2 \dot{\theta}$$

Geometrical interpretation of  $J = \text{const}$ :

Radius vector sweeps out area  $dA = \frac{1}{2} r^2 d\theta$  when angle changes by  $d\theta$ .

$$\text{So } \frac{dA}{dt} = \frac{1}{2} r^2 \dot{\theta} = \frac{J}{2m} = \text{const}$$

rate of sweeping out area is const.

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Already familiar as Kepler's 2nd Law, although it is more general i.e. applies to motion under any central force.

Alternative statement:  $v_{\theta} \propto \frac{1}{r}$  (from  $J = mrv_{\theta}$ )

## Central conservative forces conserve energy T+U Chpt 4

2 conservation laws ① Energy  $\frac{1}{2} m \dot{\vec{r}}^2 + V(r) = E = \text{const}$

② Ang. Mom.  $m \vec{r} \times \dot{\vec{r}} = \vec{J} = \text{const}$

Motion is confined to a plane and so two-dimensional  $\Rightarrow$  use polar coords:

$$\text{① } \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\theta}^2) + V(r) = E$$

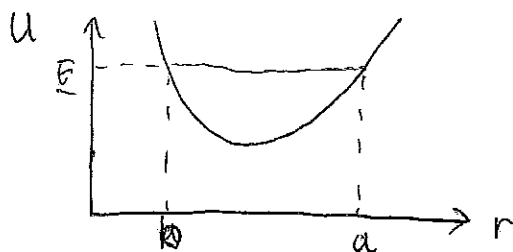
$$\text{② } m r^2 \dot{\theta} = J$$

Combine:  $\frac{1}{2} m \dot{r}^2 + \frac{J^2}{2mr^2} + V(r) = E$  radial energy eqn.

for fixed  $J$  it has form of one-dimensional energy equation with an effective potential energy

$$U(r) = \frac{J^2}{2mr^2} + V(r)$$

motion is limited to range of values of  $r$  for which  $U(r) \leq E$



(4)

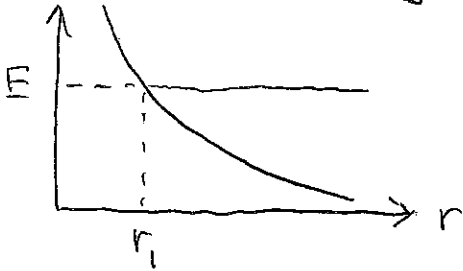
Case of the inverse square law

$$\vec{F} = \frac{k}{r^2} \hat{r} \Rightarrow V(r) = \frac{k}{r}$$

then  $\frac{1}{2} m \dot{r}^2 + \underbrace{\frac{J^2}{2mr^2} + \frac{k}{r}}_{U(r)} = E$

Repulsive case  $k > 0$

$U(r)$  decreases monotonically



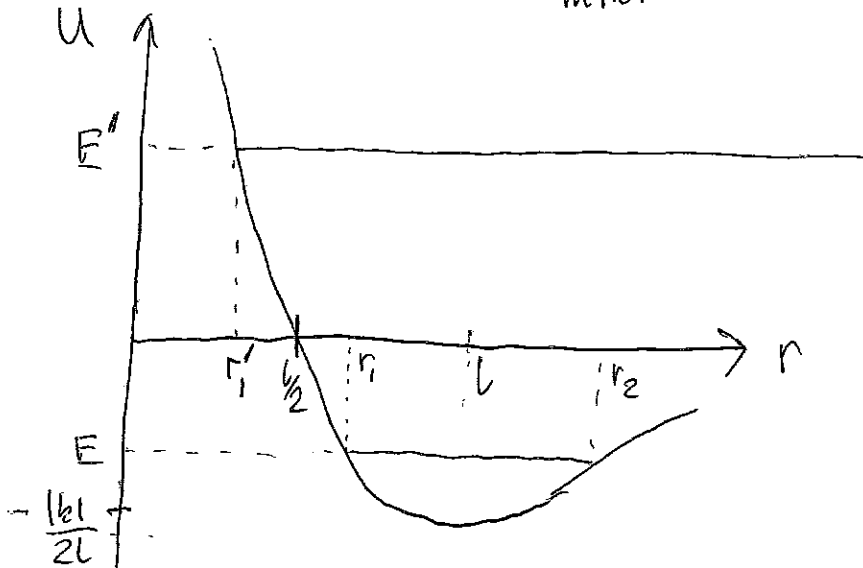
no minima: circular motion impossible.

Orbit is hyperbola (see later)

Attractive case  $k < 0$

Define a length  $l \equiv \frac{J^2}{m|k|}$

$$\Rightarrow U(r) = |k| \left( \frac{l}{2r^2} - \frac{1}{r} \right)$$



$$U\left(\frac{l}{2}\right) = 0$$

Min  $U(r)$  is at  $r = l$   
where  $U(l) = -\frac{|k|}{2l}$ .

(5)

Four cases

$$a) E = -\frac{1kl}{2l}$$

this is min of  $U \Rightarrow \dot{r} = 0$

particle moves in circle of radius  $l$

Note  $|V| = 2T$  in this case :  $V = -\frac{1kl}{l}$

N.B. Virial theorem:  $\langle V \rangle_{av} + 2\langle T \rangle_{av} = 0$

$$T = E - V = \frac{1kl}{2l}$$

$$2T + V = 0$$

Compare stho :  $T + V = \cancel{E}$   $\langle T \rangle = \langle V \rangle$

Heat capacity

$$\frac{\partial \text{Temp}}{\partial E} ?$$

$$E = T + V \quad \text{so for gravity}$$

$$\text{but } V = -2T$$

$$\text{so } E = -T$$

Associate Temp with kinetic energy  $\langle T \rangle = \frac{3}{2} k_B \text{Temp}$

so

$$E = -\frac{3}{2} k_B \text{Temp}$$

so

$$\frac{\partial \text{Temp}}{\partial E}$$

is -ve

negative  
heat capacity

$\Rightarrow$  add energy, it  
cools down!

stho

$$E = T + V = 2T$$

$$\frac{\partial T}{\partial E} > 0$$

b).  $-\frac{|k|}{2L} < E < 0$  (lower line in figure)

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radial distance  $r_1 < r < r_2$

Orbit is ellipse

c)  $E = 0$  min distance is  $r_1 = \frac{b}{2}$  but  $r_2 = \infty$

Particle can escape to infinity but with  $T=0$

orbit is parabola

d)  $E > 0$  (upper line,  $E'$ , in figure)

particle can escape to infinity but with  $T > 0$ .

orbit is hyperbola.